Generative models

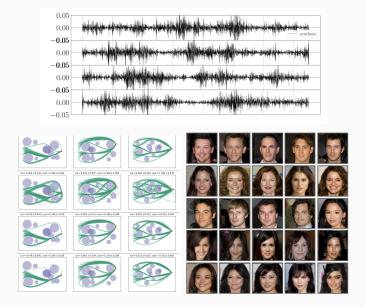
how they work and how to train them

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September 20, 2023

Intro: Generative Modelling

 x_*^1, \ldots, x_*^n : dataset drawn from an unknown distribution ρ_* ("target")



The two goals of generative modelling:

- 1. Generate 'new' samples from ρ_* (direct problem)
- 2. Find a 'good' estimator $\hat{\rho}_*$ for ρ_* (inverse problem)

Examples of generative models: EBMs, GANs, VAEs, Normalizing Flows, Neural ODEs, Noise Contrastive Estimation, Diffusions, Flow matching, Consistency models

Energy-Based Models

 $U_{\theta}: \mathbb{R}^d \to \mathbb{R}_+ =$ parametrized family of functions ("model energies")

Definition of the model densities:

$$ho_{ heta}(x) = rac{e^{-U_{ heta}(x)}}{Z_{ heta}} \qquad \qquad Z_{ heta} = \int e^{-U_{ heta}(x)} dx.$$

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Examples:

- $U_{\theta}(x) = \langle x, \theta x \rangle$ with θ a square matrix: centered Gaussian distributions
- $U_{\theta}(x) = |x \theta|$: family of Laplace distributions
- $U_{\theta}(x) =$ a complicated neural network with parameters θ : deep EBMs

The goal is to find the optimal θ_* achieving the best 'fit' between the model ρ_{θ} and the true unknown density ρ_* .

 $\theta_* \in \arg\min\operatorname{dist}(\rho_*, \rho_\theta)$

Q: how do we choose the distance?

Once U_{θ_*} has been trained, new synthetic samples are obtained by sampling from the distribution

$$\hat{\rho}_* = \rho_{\theta_*} = \frac{e^{-U_{\theta_*}}}{Z_{\theta_*}}.$$

This step typically needs MCMC methods such as Langevin:

$$X_{ au+1} = X_{ au} - \eta
abla_{ imes} U_{ heta_{st}}(X_{ au}) + \sqrt{\eta} \xi_{ au} \qquad \quad \xi_{ au} \sim \mathcal{N}(0, I)$$

This is called "implicit generation" [Du and Mordatch 19].

- **Simplicity.** Only one neural network U_{θ}
 - \rightarrow VAEs and GANs require at least two!
- Flexibility. We can exploit the tradeoff between quality and cost
 → impossible with feed-forward generators such as GANs or NFs
- Compositionality. Combining different EBMs is as simple
 → just add the energies
- Reusability. Can be used to help various other tasks
 → inpainting, importance sampling, OOD detection...

Choosing the right loss for EBM learning

 $\textbf{Kullback-Leibler divergence} \leftrightarrow \textbf{max-likelihood}$

$$\begin{split} \operatorname{dist}(\rho_{\theta}, \rho_{*}) &= \mathbb{E}_{X \sim \rho_{*}} \log \rho_{*}(X)) - \log \rho_{\theta}(X) \\ &\approx \operatorname{cst} - \frac{1}{n} \sum \log \rho_{\theta}(x_{i}^{*}) \end{split}$$

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Fisher divergence

$$dist(\rho_{\theta}, \rho_{*}) = \mathbb{E}_{X \sim \rho_{*}} |\nabla \log \rho_{*}(X) - \nabla \log \rho_{\theta}(X)|^{2}$$
$$\approx \frac{1}{n} \sum |\nabla \log \rho_{*}(x_{i}^{*}) - \nabla \log \rho_{\theta}(x_{i}^{*})|^{2}$$

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Fisher divergence

$$\begin{split} \operatorname{dist}(\rho_{\theta},\rho_{*}) &= \mathbb{E}_{X \sim \rho_{*}} \left| \nabla \log \rho_{*}(X) - \nabla \log \rho_{\theta}(X) \right|^{2} \\ &\approx \frac{1}{n} \sum \left| \nabla \log \rho_{*}(x_{i}^{*}) - \nabla \log \rho_{\theta}(x_{i}^{*}) \right|^{2} \end{split}$$

Other losses? Bregman, NCE loss, etc.

Training procedures I: max-likelihood

Gradient ascent on Energy-Based Models

Goal: maximize $L(\theta) = \mathbb{E}_*[\log \rho_{\theta}] = -\mathbb{E}_*[U_{\theta} + \log Z_{\theta}]$

$$abla_{ heta} L(heta) = -\mathbb{E}_*[U_{ heta}] -
abla \log Z_{ heta}$$

Computation of $\nabla_{\theta} \log Z_{\theta}$:

$$\frac{\nabla_{\theta} Z_{\theta}}{Z_{\theta}} = \int -\nabla_{\theta} U_{\theta}(x) e^{-U_{\theta}(x)} \frac{1}{Z_{\theta}} dx = -\mathbb{E}_{\theta} [\nabla_{\theta} U_{\theta}]$$

Gradient of the log-likelihood

$$\nabla_{\theta} L(\theta) = \mathbb{E}_{\theta} [\nabla_{\theta} U_{\theta}] - \mathbb{E}_{*} [\nabla_{\theta} U_{\theta}]$$

Gradient ascent with stepsize $\eta > 0$:

$$\theta_{t+1} - \theta_t = \eta \times \left(\mathbb{E}_{\theta_t} [\nabla_\theta U_{\theta_t}] - \mathbb{E}_* [\nabla_\theta U_{\theta_t}] \right)$$

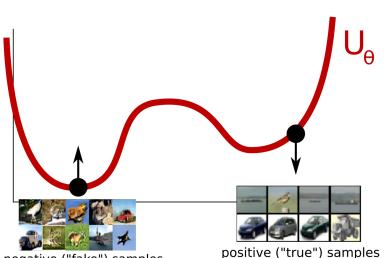
$\nabla_{\theta} L(\theta) = \nabla_{\theta} \left(\mathbb{E}_{\theta} [U_{\theta}(X)] - \mathbb{E}_{*} [U_{\theta}(X)] \right)$

 $\mathbb{E}_{*}[U_{\theta}]$ $x_{i}^{*} = \text{"positive samples"}$ from ρ_{*} $\approx \frac{1}{n} \sum_{i} U_{\theta_{t}}(x_{*}^{i})$

 $\mathbb{E}_{\theta_t}[U_{\theta}]$ $y_i = \text{"negative samples"}$ from ρ_{θ_t} $\approx \frac{1}{n} \sum_i U_{\theta_t}(y_i)$

"contrastive learning" :

- pull down the energy of positive samples, $\mathbb{E}_*[U_{\theta}]$
- pull up the energy of negative samples, $\mathbb{E}_{\theta_t}[U_{ heta}]$



negative ("fake") samples

positive ("true") samples

MCMC sampling is too costly

Q: at each gradient step, how do we get the negative samples for computing $\mathbb{E}_{\theta}[U_{\theta}]$?

A: using MCMC/Langevin methods...

At step *t*, initialize X_0^i ("walkers"), then for $\tau = 0, \ldots, T_{mix}$,

$$X^i_{ au+1} = X^i_{ au} - \eta
abla_{ imes} U_{ heta}(X^i_{ au}) + \sqrt{2\eta} \xi_{ au}$$

and estimate

$$\mathbb{E}_{ heta_t}[U_{ heta_t}] pprox rac{1}{N_{ extsf{walkers}}} \sum_{i=1}^{N_{ extsf{walkers}}} U_{ heta_t}(X^i_{T_{ extsf{mix}}}).$$

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If T_{mix} is large, this is too costly.

Each gradient ascent step will consume T_{mix} MCMC sampling steps for each of the $N_{walkers}$ chains!

- don't let the chain reach T_{mix} steps. Use only k steps (k = 1).
- initialize each chain directly at the training points $\{x_*^i\}$.

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[Yair and Michaeli 20] CD-1 is an adversarial game [Agoritsas et al 23] Effect of non-convergent sampling

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Practically: maintain a set of walkers X_t^i . At step t + 1,

- 1) approximate $\mathbb{E}_{\theta_t}[U_{\theta_t}] \approx \frac{1}{n} \sum_{i=1}^N U_{\theta_t}(X_t^i)$,
- 2) compute θ_{t+1} using the approximation,
- 3) move the walkers with $X_{t+1} = X_t \eta \nabla U_{\theta_{t+1}}(X_t) + \sqrt{2\eta} \xi$

 \Rightarrow leads to mode collapse.

- don't let the chain reach T_{mix} steps. Use only k steps (k = 1).
- Initialize each chain directly at the training points $\{x_*^i\}$.
- initialize each chain directly where the previous chain ended.
- initialize, sometimes from the past, sometimes from pure noise
- + many other tricks.

Training procedures II: alternative losses

- a Noise Contrastive methods
- b GANs
- c Score Matching
- d Denoising score matching

a. Noise Contrastive Estimation [Gutmann & Hyvarinen 2010]

Let μ be a known density and $y_i \sim \mu$ be iid.

Idea: train a binary classifier with logistic regression to distinguish between true samples x_i^* and fake samples y_i .

Bayes' rule gives the optimal classifier D_{opt} :

$$egin{aligned} D_{ ext{opt}}(x) &= \mathbb{P}(extsf{true} \mid x) = rac{p(x \mid extsf{true})}{p(x \mid extsf{fake}) + p(x \mid extsf{true})} \ &= rac{
ho_*(x)}{
ho_*(x) + \mu(x)} \end{aligned}$$

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ho_*(x)}{
ho_*(x) + \mu(x)} \end{aligned}$$

Goal: maximize $R(\theta) = \sum_{i=1}^{n} \log D_{\theta}(x_i^*) + \log(1 - D_{\theta}(y_i)).$ Set $D_{\theta}(x) = F_{\theta}(x)/(F_{\theta}(x) + \mu(x))$ with $F_{\theta}(x) = e^{-U_{\theta}(x) + c_{\theta}}.$ If $D_{\theta_*} \approx D_{opt}$ then $F_{\theta_*} \approx \rho_*$

The normalization $\int e^{-U_{\theta}+c_{\theta}} = 1$ is automatic!

- if μ is too close to ρ_* then training the classifier is too difficult
- if μ is too different to ρ_{*} then classifying is too easy, there are near-optimal classifiers very different than the optimal one

the GAN idea

 \Rightarrow also train a "fake sample generator", say $\mu_\beta,$ instead of using always the same fixed generator μ

GAN objective: $\min_{\theta} \max_{\beta} \mathbb{E}_*[\log D_{\theta}] + \mathbb{E}_{\mu_{\beta}}[\log(1 - D_{\theta})]$ Min-Max problems are hard.

c. Score Matching [Hyvarinen 2005]

Goal: minimize $SM(\theta) = \mathbb{E}_*[|\nabla \log \rho_{\theta} - \nabla \log \rho_*|^2].$

Hyvarinen 2005

$$SM(\theta) = \operatorname{cst} + \mathbb{E}_*[|\nabla \log \rho_{\theta}|^2 + 2\Delta \log \rho_{\theta}].$$

- Parametrize the score $\nabla \log \rho_{\theta}$ with a neural network s_{θ}
- Minimize $\mathbb{E}_*[|s_{\theta}|^2 + 2\nabla_x \cdot (s_{\theta})]$ using gradient descent

Problem 1: for $\nabla_{\theta} SM(\theta)$ we need to compute "double derivatives" like

 $\nabla_{\theta} \nabla_{x} \cdot \mathbf{s}_{\theta}(x).$

Problem 2: inferring log ρ from $s_{\theta} \approx \nabla \log \rho_{\theta}$?

Proof of Hyvarinen's identity: it's just an integration by parts. For p, q two smooth densities with fast decay at ∞ ,

$$\begin{split} \mathbb{E}_{p}[|\nabla \log p - \nabla \log q|^{2}] &= \int p |\nabla \log p - \nabla \log q|^{2} \\ &= \int p |\nabla p/p - \nabla q/q|^{2} \\ &= c_{p} + \int p |\nabla/q|^{2} - 2 \int \nabla p \cdot \nabla \log q \\ &= c_{p} + \int p |\nabla \log q|^{2} + 2 \int p \nabla \cdot \nabla \log q \\ &= c_{p} + \mathbb{E}_{p}[|\nabla \log q|^{2} + 2\Delta \log q] \end{split}$$

Let us corrupt the original samples with noise:

$$y_i^* = x_i^* + \epsilon_i \qquad \epsilon_i \sim \mathcal{N}(0, \sigma^2)$$

distribution of $y_i^* = \rho_* * \mathcal{N}$.

Vincent 2009

$$SM(\theta) = \operatorname{cst} + \mathbb{E}_{X \sim \rho_*, \varepsilon \sim g}[|\nabla \log g(\varepsilon) - \nabla \log \rho_{\theta}(X + \varepsilon)|^2]$$

- Parametrize the score of the noisy distribution with s_{θ} (NN)
- Minimize $\mathbb{E}[|\epsilon/\sigma s_{\theta}(X + \epsilon)|^2]$
- \Rightarrow no double derivatives!

1) In the presence of high energy barriers, SM methods and variants cannot learn the relative weights of the modes and/or lead to mode collapse.

- 2) The score $s_{\theta_*} \approx \nabla \log \rho_*$ does not give direct access to the density!
- 3) Results were good... but not as good as GANs

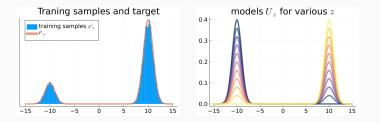
Training procedures III: some insights from toy models

Model: all gaussian mixtures with modes a = -10, b = 10:

$$U_z(x) = -\log\left(e^{-|x-a|^2/2} + e^{-z}e^{-|x-b|^2/2}\right)$$

$$Z_z = (1+e^{-z})\sqrt{2\pi}$$

$$\rho_z(x) = \frac{e^{-|x-a|^2/2} + e^{-z}e^{-|x-b|^2/2}}{(1+e^{-z})\sqrt{2\pi}}$$



Target: $\rho_* = \rho_{z_*}$ for some z_* with $q_* = \frac{e^{-z_*}}{1+e^{-z_*}} \approx 0.8$.

Useful approximations

$$\nabla_x U_z(x) = \frac{(x-a)e^{-(x-a)^2/2} + e^{-z}(x-b)e^{-(x-b)^2/2}}{e^{-(x-a)^2/2} + e^{-z}e^{-(x-b)^2/2}}$$
$$\approx (x-a)\mathbf{1}_{x \text{ close to } a} + (x-b)\mathbf{1}_{x \text{ close to } b}$$

$$abla_z U_z(x) = e^{-z} e^{-(x-b)^2/2}/U_z(x) pprox 1_x$$
 is close to b

 $\forall z, w$ $\mathbb{E}_w[\nabla_z U_z] \approx \mathbb{P}_w(\text{ mode } b) = \frac{e^{-w}}{1+e^{-w}}$

Gradient flow (continuous version of the discrete gradient descent):

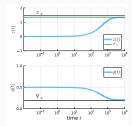
$$\dot{z}(t) = -\nabla_z \operatorname{loss}(\rho_*, \rho_{z(t)})$$

where loss is one of the various objectives above.

Success of max-likelihood

$$\dot{z}(t) = \mathbb{E}_{z(t)}[
abla_z U_{z(t)}] - \mathbb{E}_{z_*}[
abla_z U_{z(t)}] \ pprox rac{e^{-z(t)}}{1+e^{-z(t)}} - rac{e^{-z_*}}{1+e^{-z_*}}.$$

Clearly this system converges towards its unique FP $z(t) = z_*$.

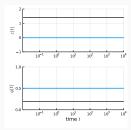


$$\dot{z}(t) = -\nabla_z SM(z) = \nabla_z \mathbb{E}_{z_*}[|\nabla \log \rho_{z(t)} - \nabla \log \rho_{z_*}|^2]$$

Remember that

$$abla \log
ho_z(x) pprox (x-a) 1_x$$
 close to $_a + (x-b) 1_x$ close to $_b$

 $\Rightarrow \nabla \log \rho_z(x) \text{ does not depend on } z, \text{ hence } \nabla_z SM(z) \approx 0.$ This leads to the "no learning" phenomenon $\dot{z}(t) \approx 0$



Mode collapse in PCD

Here the negative samples are generated using

$$dX_t = -\nabla_x U_{z(t)}(X_t) dt + \sqrt{2} dB_t$$

Remember that

$$abla_x U_z(x) pprox (x-a) \mathbb{1}_x$$
 close to $_a + (x-b) \mathbb{1}_x$ close to $_b$

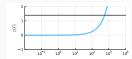
 X_t close to $b \Rightarrow dX_t \approx -(X_t - b)dt + \sqrt{2}dB_t$: Ornstein-Uhlenbeck X_t close to $a \Rightarrow dX_t \approx -(X_t - a)dt + \sqrt{2}dB_t$: Ornstein-Uhlenbeck

There is no transfer of walkers between modes a and b!

The distribution of X_t does not change and is equal to $\rho_{z(0)}$:

$$\dot{z}(t) pprox rac{e^{-z(0)}}{1+e^{-z(0)}} - rac{e^{-z_*}}{1+e^{-z_*}} = \mathrm{cst}$$

This leads to mode collapse, $z(t) \rightarrow \pm \infty$.



Thanks for the invitation!





École des Ponts ParisTech



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How to train your EBMs (Song & Kingma)
Score Matching (Hyvarinen)
Denoising score matching (Vincent)
Noise contrastive estimation (Gutman and Hyvarinen)
Conditional NCE (Ma and Collins)
Improved CD (Du et al.)
Implicit generation (Du et al.)
Reduce, Reuse, Recycle (Du et al.)
Efficient training of EBMs (Carbone et al.)
From SM to diffusion models (Song and Ermon)
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